

2.3 Lie groups, $SU(N)$

Lie groups represent continuous symmetries, e.g. rotations. To build gauge theories, we are interested in groups with finite-dim unitary representations, so called compact Lie groups.

We are interested in groups which can be generated

from repeated action of an infinitesimal group element

$$g(\alpha) = 1 + i\alpha^a t^a + O(\alpha^2)$$

↙ "generators"

The structure of the group is determined by the commutation relations

$$[t^a, t^b] = if^{abc} t^c$$

↖ "structure constants"

⌈ Note Baker-Campbell-Hausdorff

$$e^{i\alpha \cdot t} e^{i\beta \cdot t} = e^{i(\alpha+\beta) \cdot t - \frac{1}{2} [\alpha \cdot t, \beta \cdot t] + \dots}$$

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Terminology for Lie groups

Simple: Cannot split generators in two commuting sets

Semi-simple: Does not contain generators which commutes with all others, i.e. no $U(1)$ factors.

Jacobi identity,

$$[t^a, [t^b, t^c]] + [t^b, [t^c, t^a]] + [t^c, [t^a, t^b]] = 0$$

implies

$$[[T^a, i f^{bcd} T^d]] = i f^{ade} f^{bcd} T^e + \dots$$

$$f^{ade} f^{bcd} + f^{bde} f^{acd} + f^{cde} f^{abd} = 0$$

There exist only a small number of such groups (Killing & Cartan)

1.) SU(N) $\xrightarrow{\mathbb{C}} U(N)$ (\mathbb{C} complex)

Complex n -dim unitary matrices $U^\dagger U = 1$

with $\det(U) = 1$

$N^2 - 1$ generators, which are Hermitian traceless

matrices $T^\dagger = T$ $\text{tr}(T) = 0$

2.) Orthogonal transformations $UU^T = 1$ of n -dim vectors. Rotation group.

$N(N-1)/2$ generators

3.) Symplectic transformations of N -dim. vectors $Sp(N)$. These trafs leave the product

$$\vec{y}^T E \vec{x} \text{ invariant } E = \begin{pmatrix} 0 & \mathbb{1}_{N \times N} \\ -\mathbb{1}_{N \times N} & 0 \end{pmatrix}$$

it has $N(N+1)/2$ generators

In addition, there are five exceptional lie algebras denoted by

$$G_2, F_4, E_6, E_7, E_8$$

A d-dim representation R is a set of $d \times d$ matrices which satisfy the commutation relations.

Choose t_R^a such that

$$\text{tr} [t_R^a t_R^b] = \text{Tr}_R f^{ab}$$

For each representation, there is a complex conjugate rep.

$$\phi \rightarrow (1 + i \alpha^a t_R^a) \phi$$

$$\phi^* \rightarrow (1 - i \alpha^a (t_R^a)^*) \phi$$

$$\Rightarrow t_R^a = -(t_R^a)^* = -(t_R^a)^T.$$

The structure constants f_{abc} form a representation, the so-called adjoint repr.

$$(t_A^c)_{ab} = -i f_{abc}$$

The commutation relations for t_A^c are the Jacobi identity.

The simplest representation for $SU(N)$ is on the space of N -dim vectors and is called the fundamental rep.

We choose t^a , such that

$$(*) \quad \text{tr} \left[t_{\mathbb{F}}^a t_{\mathbb{F}}^b \right] = T_{\mathbb{F}} \delta^{ab} = \frac{1}{2} \delta^{ab}$$

The Casimir operator $T_{\mathbb{R}}^2 = \sum_a t_{\mathbb{R}}^a t_{\mathbb{R}}^a$ commutes with all group elements. For an irreducible representation, it follows (Schur's lemma)

$$T_{\mathbb{R}}^2 = C_{\mathbb{R}} \cdot \mathbb{1}.$$

Irreducible: block diagonalize representation. If there is only 1 block, the rep. is irred.

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Let's calculate $C_{\mathbb{F}}$ for $\mathfrak{su}(N)$

$$\text{tr} \left[t_{\mathbb{F}}^a t_{\mathbb{F}}^a \right] = \frac{1}{2} \sum_{a,b} \delta^{ab} = \frac{1}{2} (N^2 - 1)$$

$$= \text{tr} \left[C_{\mathbb{F}} \mathbb{1} \right] = C_{\mathbb{F}} N$$

$$\Rightarrow C_{\mathbb{F}} = \frac{N^2 - 1}{2N}$$

Without proof $C_A = N$.

An explicit basis of generators for $su(3)$

are the Gell-Mann matrices

$$t^1 = \frac{\lambda^1}{2} = \frac{1}{2} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad t^2 = \frac{1}{2} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

... (see any book)

$$t^8 = \frac{1}{2\sqrt{3}} \begin{pmatrix} 1 & & \\ & 1 & \\ & & -2 \end{pmatrix}.$$

However, in practice one avoids the explicit rep. and tries to express everything in terms of Casimir invariants, or uses the Fierz relation of $su(N)$

$$t_{ij}^a t_{ke}^a = \frac{1}{2} \left(\delta_{ie} \delta_{kj} - \frac{1}{N} \delta_{ij} \delta_{ke} \right)$$